
Subject: Need a suggestion about mouse processing inside threads

Posted by [mdelfede](#) on Mon, 12 Dec 2011 23:53:47 GMT

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Hi, I've a multi-document application, on which each document runs a threaded command loop :

```
// document command loop
void UppCadDocument::commandLoop(void)
{
    // loop not ended
    INTERLOCKED_(mutex)
    {
        loopEnded = false;
    }
    while(!Thread::IsShutdownThreads())
    {

        if(commandLine.HasCommand())
        {
            String cmd = commandLine.GetCommand();
            if(cmd != "<ESC>" && cmd != "")
                SendCommand(cmd);
        }
        Sleep(100);
    }
    // loop ended
    INTERLOCKED_(mutex)
    {
        loopEnded = true;
    }
}
```

Here, handling of commandLine (some sort of InputField) is simple; the problem arise when I've to react to mouse events; main thread can call, for example, MouseMove() on any time in the middle of anything of my document's loop.

How to synchronize it ? I can't stop my main thread waiting for a document's one is ready for event, of course... I think I'd need some sort of event-loop inside document's threads, and main thread should inject its events on it, instead executing calls directly, but how ?

This is exactly the opposite problem as the one solvable with Guilock....

My idea would be something like this :

Main thread :

```
void SomeEventHandler(somedata)
```

```
{
    GetActiveDocument().InjectEvent(eventtype, somedata);
}
```

Document thread :

```
while(true)
{
    WaitForInjectedEventsWithoutEatingCpu();
    while(eventsInQueue)
        ProcessPendingEvents()
}
```

Is there something in upp that can help for all that, or I should code it using arrays of callbacks or something like that ?
Or there's a better solution ?

Max

Subject: Re: Need a suggestion about mouse processing inside threads
Posted by [mirek](#) on Tue, 13 Dec 2011 16:47:56 GMT
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From what I see, the only thing you need is to synchronize is your commandline. So just create Mutex for reading/writing to commandline...

Not that you will have to make a copy when reading it...

```
void UppCadDocument::commandLoop(void)
{
    // loop not ended
    INTERLOCKED_(mutex)
    {
        loopEnded = false;
    }
    while(!Thread::IsShutdownThreads())
    {
        String currentCommand;
        {
            Mutex::Lock ____(commandLineMutex)
            currentCommand = commandLine;
        }
        if(currentCommand.HasCommand())
```

```

{
    String cmd = currentCommand.GetCommand();
    if(cmd != "<ESC>" && cmd != "")
        SendCommand(cmd);
}
Sleep(100);
}
// loop ended
INTERLOCKED_(mutex)
{
    loopEnded = true;
}
}

```

Subject: Re: Need a suggestion about mouse processing inside threads

Posted by [mdelfede](#) on Tue, 13 Dec 2011 16:53:47 GMT

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I guess it's not so simple.... What about mouse events ?

They come from main thread, go into view (which belongs to document running its own thread) and calls document functions asynchronously.

I say that because I tested it and it behaves quite weird.

By now I'm trying to re-direct all gui events from main thread into a FIFO inside each document, which is then processed synchronously by document thread.... Still don't know if it will work as I expect. I see the matter quite tricky....

Max

Subject: Re: Need a suggestion about mouse processing inside threads

Posted by [mdelfede](#) on Tue, 13 Dec 2011 17:00:18 GMT

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Just to explain a bit more my thoughts....

Managing code (class ThreadQueue, which is a direct parent of UppCadDocument:)

```

// wait for next event and process it
// returns false if shutting down
bool ThreadQueue::WaitAndProcessEvent(void)
{

```

```

// test again if shutting down
if(Thread::IsShutdownThreads() || exiting)
    return false;

// wait for events
semaphore.Wait();

// test again if shutting down
if(Thread::IsShutdownThreads() || exiting)
    return false;

Callback c;

// pops next event
INTERLOCKED_(mutex) {
    ASSERT(!queue.IsEmpty());
    c = queue.Head();
    queue.DropHead();
}

// runs the callback
c.Execute();

// test again if shutting down
if(Thread::IsShutdownThreads() || exiting)
    return false;

return true;
}

// sends an event to this thread
void ThreadQueue::SendEvent(Callback c)
{
    INTERLOCKED_(mutex) {
        queue.AddTail(c);
        semaphore.Release();
    }
}

```

Document loop :

```

// document command loop
void UppCadDocument::commandLoop(void)
{
    while(WaitAndProcessEvent())

```

```

{
  if(commandLine.HasCommand())
  {
    String cmd = commandLine.GetCommand();
    if(cmd != "<ESC>" && cmd != "")
      SendCommand(cmd);
  }
}

```

And, for example, a view mouse event handling :

```

////////////////////////////////////
// middle up - resets pan/3dorbit behaviour
void UppCadView::MiddleUp(Point p, dword keyflags)
{
  SendViewEvent2(uppCadDocument. MiddleUp0, p, keyFlags);
}

void UppCadView::MiddleUp0(Point p, dword keyflags)
{
  isPanning = false;
  PanStartPoint.SetNull();

  isRotating = false;
} // END UppCadView::MiddleUp()

```

(SendViewEvent2 is a macro calling uppCadDocument::SendEvent() with correct parameters)

Subject: Re: Need a suggestion about mouse processing inside threads
 Posted by [mdelfede](#) on Tue, 13 Dec 2011 17:49:17 GMT
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Well... it doesn't work either
 Gui is not updated if running inside doc thread....

Subject: Re: Need a suggestion about mouse processing inside threads
 Posted by [mdelfede](#) on Mon, 19 Dec 2011 14:58:00 GMT
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Solved with a separated processong queue per thread

For whom is interested, here a small class :

ThreadQueue.h :

```
#ifndef _ThreadQueue_ThreadQueue_h
#define _ThreadQueue_ThreadQueue_h
```

```
#include <Core/Core.h>
```

```
using namespace Upp;
```

```
class ThreadQueue
```

```
{
private:
```

```
    // thread running loop;
    Thread loopThread;
```

```
    // loop call function
    void callLoop(Callback cb);
```

```
    // the queue/fifo
    BiVector<Callback> queue;
```

```
    // controlling semaphore
    Semaphore semaphore;
```

```
    // sync mutex
    Mutex mutex;
```

```
    // exiting flag -- to manually shutdown
    bool exiting;
```

```
    // exited flag
    bool exited;
```

```
protected:
```

```
public:
```

```
    typedef ThreadQueue CLASSNAME;
```

```
    // constructor
    ThreadQueue();
```

```
    // destructor
```

```

~ThreadQueue();

// sends an event to this thread
void SendEvent(Callback c);

// wait for next event and process it
// returns false if shutting down
bool WaitAndProcessEvent(void);

// shutdown this thread
// returns true if successfully shut down after some
// wait time, false if loop is blocked somehow
bool Shutdown(void);

// ask if we're exiting from thread loop
bool Exiting(void);

// ask if thread exited
bool Exited(void);

// start the command loop
void StartLoop(Callback cb);
};

#endif

```

ThreadQueue.cpp :

```

#include "ThreadQueue.h"

// constructor
ThreadQueue::ThreadQueue()
{
    // not exited on startup
    exited = false;

    // end not exiting too....
    exiting = false;
}

// destructor
ThreadQueue::~ThreadQueue()
{
    // try to exit loop on destruction, if not already out
    Shutdown();
}

```

```

// loop call function
void ThreadQueue::callLoop(Callback cb)
{
    INTERLOCKED_(mutex) {
        exited = false;
    }
    cb();
    INTERLOCKED_(mutex) {
        exited = true;
    }
}

// wait for next event and process it
// returns false if shutting down
bool ThreadQueue::WaitAndProcessEvent(void)
{
    // test again if shutting down
    if(exiting)
        return false;

    // wait for events
    semaphore.Wait();

    // test again if shutting down
    if(exiting)
        return false;

    Callback c;

    // pops next event
    INTERLOCKED_(mutex) {
        ASSERT(!queue.IsEmpty());
        c = queue.Head();
        queue.DropHead();
    }

    // runs the callback
    c.Execute();

    // test again if shutting down
    if(exiting)
        return false;

    return true;
}

// sends an event to this thread

```



```

void ThreadQueue::SendEvent(Callback c)
{
    INTERLOCKED_(mutex) {
        queue.AddTail(c);
        semaphore.Release();
    }
}

// shutdown this thread
// returns true if successfully shut down after some
// wait time, false if loop is blocked somehow
bool ThreadQueue::Shutdown(void)
{
    // if already out of loop, just return true
    if(Exited())
        return true;

    // signals that we wanna exit
    INTERLOCKED_(mutex) {
        exiting = true;
    }

    // send a fake event to unlock event waiting
    SendEvent(Callback());

    // wait to give time for loop exiting
    // here about 1s wait max
    for(int i = 0; i < 10; i++)
    {
        if(Exited())
            return true;
        // send a fake event to unlock event waiting
        SendEvent(Callback());
        Sleep(100);
    }

    // if here, thread loop is still busy
    return false;
}

// ask if thread exited
bool ThreadQueue::Exited(void)
{
    bool ex;
    INTERLOCKED_(mutex) {
        ex = exited;
    }
    return ex;
}

```

```

}

// ask if thread exited
bool ThreadQueue::Exiting(void)
{
    bool ex;
    INTERLOCKED_(mutex) {
        ex = exiting;
    }
    return ex;
}

// start the command loop
void ThreadQueue::StartLoop(Callback cb)
{
    exiting = exited = false;
    loopThread.Start(THISBACK1(callLoop, cb));
}

```

Usage is self explained by comments... I hope.

In short, it's enough to derive a class from ThreadQueue, and you'll have the ability to run a loop which can wait for external messages and process them; the messages are read synchronously one after other like a normal gui message loop.

Here an example of thread loop function :

```

// document command loop
void UppCadDocument::commandLoop(void)
{
    while(WaitAndProcessEvent())
    {
        if(commandLine.HasCommand())
        {
            String cmd = commandLine.GetCommand();
            if(cmd != "<ESC>" && cmd != "")
                SendCommand(cmd);
            GetCurrentView()->RefreshView();
        }
    }
}

```

The loop waits from an event injected from gui, when it comes check some command line stuff and, if any, process the command inside thread; then it'll stop waiting again.

The WaitAndProcessEvent() function has internal logic to handle a shutdown flag.

Max
